

# Contacting Pedal Assembly

## **TYPICAL APPLICATIONS:**

Accelerator pedal for electronic throttle control systems

## Features/Benefits:

- Fully redundant, dual output contacting electrical sensor integrated into pedal assembly
- Analog output signal
- Dual load/return force generation in compliance with FMVSS 124
- Self adjusting hysteresis control
- Mechanical kickdown feature optional
- Compact size, approximate weight 300 g
- Six pin connector
- Optional electrical output customizable to customer-specific application requirements
- Pedal arm configuration customizable to customerspecific application requirements

# **TYPICAL SPECIFICATIONS:**

#### **ELECTRICAL**

See Figure 1 Linearity (absolute): 0° to 17° Rotation (electrical): Rotation (mechanical): 0° to 18°  $5\,\mathrm{V}_{\mathrm{DC}}$ Typical Input Voltage: 15 V<sub>DC</sub> See Figure 3 Overall Voltage: Track Correlation:

### **MECHANICAL**

See Figure 2 Pedal Stepping Force: Internal End Stop Strength: 900 N Sideload Strength: 300 N

## **DURABILITY**

Operating Temp. Range: -40° to 80°C Life Cycles: 3 x 10<sup>6</sup> cycles

Vibration: 5 to 100 Hz @ 0.2 to 1.6 g; 8 hrs. each plane

-40° to 80°C; 500 shock cycles Thermal Shock: ESD (powered): ± 15 KV, terminal discharge

#### **ENVIRONMENTAL**

Salt Spray: 24 hrs. (5% NaCl) Humidity: 144 hrs. @ 95% RH

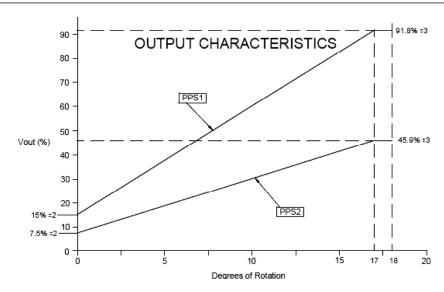












Standard output shown. Both outputs are fully adjustable to suit customer-specific needs.

#### **HEADQUARTERS:**

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# FIGURE 2 — TYPICAL MECHANICAL OUTPUT

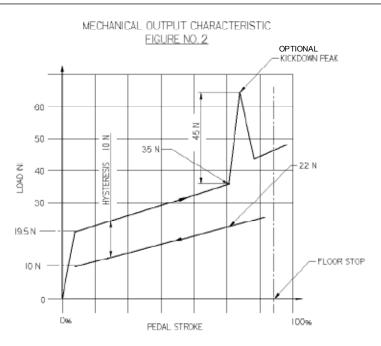
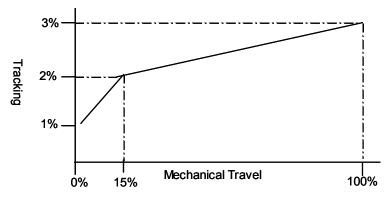


FIGURE 3 — TRACK CORRELATION



Signal 2 required defined with respect to Signal 1

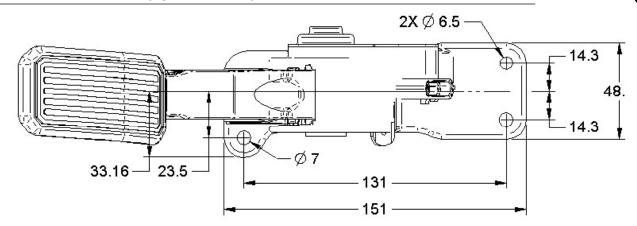
 $\frac{\text{Signal 1}}{\text{Supply 1}} = 2 \times \frac{\text{Signal 2}}{\text{Supply 2}}$ 

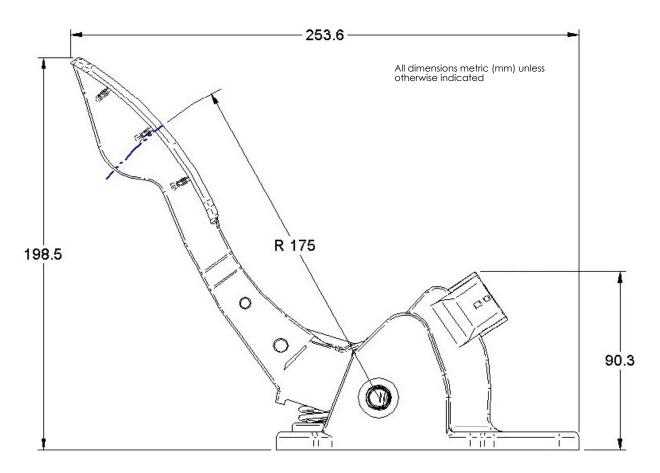
Tracking value error as per Figure 3 shown

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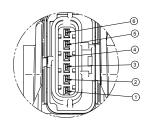


# DIMENSIONAL DETAILS





# CONNECTOR PIN-OUT INFORMATION



DESIGNATION
GROUND PPS2
GROUND PPS1
OUTPUT PPS1
SUPPLY PPS1
SUPPLY PPS2
OUTPUT PPS2